

5. PRODUCTOS DE INVESTIGACIÓN Y DESARROLLO.

5.1 PUBLICACIONES DE LOS INVESTIGADORES

5.1.1. Artículos originales de investigación:

a) Publicados en extenso en revistas de prestigio internacional con arbitraje estricto.

1. C. Cariño Escobar, R. Lozano, **M. Bonilla Estrada**. "PVTOL control using feedback linearisation with dynamic extension". *International Journal of Control*, 10 pp, 2019. <https://doi.org/10.1080/00207179.2019.1676468>.
2. D. Bonilla Licea, **M. Bonilla**, M. Ghogho, S. Lasaulce, V.S. Varma. "Communication-Aware Energy Efficient Trajectory Planning With Limited Channel Knowledge". *IEEE TRANSACTIONS ON ROBOTICS*, 12 pp, 2019. <https://doi.org/10.1109/TRO.2019.2948801>.
3. C. Cariño Escobar, R. Lozano, **M. Bonilla Estrada**. "Two PVTOLs Cooperative Slung Load Transport Control Based on Passivity". *Advanced Control for Applications: Engineering and Industrial Systems*, 22 pp, 2019. <https://doi.org/10.1002/adc2.22>.
4. **M. Bonilla**, L.A. Blas, V. Azhmyakov, M. Malabre, S. Salazar. "Robust structural feedback linearization based on the nonlinearities rejection". *Journal of the Franklin Institute*, 31 pp, 2019. <https://doi.org/10.1016/j.jfranklin.2019.11.044>
5. Félix Miranda, **Fernando Castaños** y Bernard Brogliato; Continuous and discrete-time stability of a robust set-valued nested controller; *Automatica*, (2019) 107:406 – 417
6. Carlos Aguilar-Ibanez, Hebertt Sira-Ramirez, Miguel S. Suarez-Castanon and **Ruben Garrido**. Robust trajectory tracking control of a PVTOL under crosswinds, *Asian Journal of Control*. (2019), Vol. 21, No. 3, pp 1293–1306.
7. C. Franco and **J. Collado**. A novel discriminant approximation of periodic differential equations. *Journal of Differential Equations*. 2019, Vol. 266, pp. 5448-5487.
8. Arturo Díaz, **Rubén Garrido**, J.J. Soto-Bernal. A Filtered Sun Sensor for Solar Tracking in HCPV and CSP Systems. *IEEE Sensors Journal*. (2019), Vol. 19, No.3, pp 917-925.
9. **Rubén Garrido**, Miguel A. Trujano. On visual PID control of a perturbed planar parallel robot under Jacobian Uncertainties. *International Journal of Control, Automation and Systems*. (2019), Vol. 17, No. 6, pp 1589-1598.
10. J. Maldonado, L. Luna, **R. Garrido**, G. Castro. A Teaching Methodology Based on an Educational Experimental Platform. *IEEE Latin America Transactions* (2019). Vol. 17, No. 8, pp 1363-1370.
11. Ramírez A, Sipahi R., **Mondié S., Garrido R**. Fast consensus in a large-scale multi-agent system with directed graphs using time-delayed measurements. *Phil. Trans. R. Soc. A*. (2019), Vol. 377, No. 2153, pp. 20180130.
12. Ramírez-Neria, H. Sira-Ramírez, **R. Garrido-Moctezuma** and A. Luviano-Juárez. Active Disturbance Rejection Control of the Inertia Wheel Pendulum through a Tangent Linearization Approach. *International Journal of Control, Automation and Systems*. (2019), Vol. 17, No. 1, pp 18–28.
13. Elisa Alòs, Antoine Jacquier y **Jorge A. León**. The implied volatility of forward-start options: ATM short-time level, skew and curvature. *Stochastics, An International Journal of Probability and Stochastic Processes* 91, (1), 37-51, 2019. Doi: 10.1080/17442508.2018.1499105.
14. Elisa Alòs y **Jorge A. León**, A note on the implied volatility of floating strike Asian options. *Decisions in Economics and Finance* 42, 743-758, 2019.
15. **J. Morales-Valdez**, L. Alvarez-Icaza, and J. Escobar-Sánchez. "Online Identification System for Damage Location in Building Structures". *IEEE Latin American Transaction*, 17(08), Pag 128-1290. 2019
16. Iván Trejo-Zúñiga, Sergio M. Delfín-Prieto and **Rafael Martínez-Guerra**, "Fractional controller based on a robust PI α observer for uncertain fractional systems", *International Journal of Systems Science*, 50, 4, pp. 829-842, 2019.
17. Javier Montesino-Garcia and **Rafael Martínez-Guerra**, "A numerical estimation of the fractional-order Liouvillian systems and its application to secure communications", *International Journal of Systems Science*, 50, 4, pp. 791-806, 2019.
18. Oscar Martínez-Fuentes, **Rafael Martínez-Guerra**, "A High-Gain Observer with Mittag-

- Leffler rate of Convergence for a Class of Nonlinear Fractional-Order Systems”, *Communications in Nonlinear Science and Numerical Simulation*, 79, 104909, 2019.
19. Juan Pablo Flores-Flores, **Rafael Martínez-Guerra**, “PI Observer design for a Class of Nondifferentially Flat Systems”, *International Journal of Applied Mathematics and Computer Science*, 29, 4, pp. 655-665, 2019.
 20. Sergio Miguel Delfin-Prieto, **Rafael Martínez-Guerra**, A Mittag-Leffler fractional-order difference Observer, *Journal of the Franklin Institute*, <https://doi.org/10.1016/j.jfranklin.2019.12.009> .
 21. Marco A. Gomez, Wim Michiels, **Sabine Mondié**, Design of delay-based output-feedback controllers optimizing a quadratic cost function via the delay Lyapunov matrix, *Automatica*, 107(9), 146-153, 2019.
 22. Marco A. Gomez, Alexey V. Egorov, **Sabine Mondié**, Lyapunov matrix based necessary and sufficient stability condition by finite number of mathematical operations for retarded type systems, *Automatica* 108(10),108475, 2019.
 23. Marco A. Gomez, Alexey V. Egorov and **Sabine Mondié**, Necessary stability conditions for neutral-type systems with multiple commensurate delays, *International Journal of Control*, 92(5), 1155-1166, 2019
 24. Marco A. Gomez, Alexey V. Egorov, **Sabine Mondié**, Alexey P. Zhabko, Computation of the Lyapunov matrix for periodic time-delay systems and its application to robust stability analysis *Systems & Control Letters*, 132, 104501, 2019.
 25. Marco A. Gómez, Alexey V. Egorov , **Sabine Mondié** , and Wim Michiels, Optimization of the H_2 Norm for Single-Delay Systems, With Application to Control Design and Model Approximation, *IEEE Transactions On Automatic Control*, 64(2) 804-811, 2019.
 26. Juárez and **Mondié S.**, Dynamic Predictor-based Controls: A Time-domain Stability Analysis, *IEEE Latin America Transactions*, 17(7), 1207-1213, 2019.
 27. GONZALEZ, A. J.; SERNA, J.; FORY, C.; OJEDA, A.; CARDONA, J.; TOMBÉ, J. & **SORIA, A.**- “A Low-Cost, Free-Software Platform with Hard Real-Time Performance for Control Engineering Education”. *Computer Applications in Engineering Education*. DOI: 10.1002/cae.22084. Vol. 27, N°2. pp. 406-4018. 2019
 28. PERRUSQUÍA, A; **WEN, Y.**; **SORIA, A.**- Position/force control of robot manipulators using reinforcement learning. *Industrial Robot*. Vol.46, N° 2. pp. 267-280. 2019.
 29. Lourdes Esteva, **Cristobal Vargas**, Hyun Mo Yang, A model for yellow fever with migration, *Computational and Mathematical Methods*; DOI: 10.1002/cmm4.1059.
 30. Sina Razvarz, **Cristóbal Vargas-Jarillo**, Raheleh Jafari, Alexander Gegov, Flow Control of Fluid in Pipelines Using PID Controller;; *IEEE Access*; DOI: 10.1109/ACCEESS.2019.2897992.
 31. J. Guerrero, **J. Torres**, V. Creuze and A. Chemori, “Trajectory tracking for autonomous underwater vehicle: An adaptive approach”, *Ocean Engineering*, vol. 172, pp 511-522, (2019)
 32. E. Campos, J. Monroy, H. Abundis, A. Chemori, V. Creuze and **J. A. Torres**, “A nonlinear controller based on saturation functions with variable parameters to stabilize an AUV”, *International Journal of Naval Architecture and Ocean Engineering*, Vol. 11, Issue 1, pp 211-224, (2019)
 33. J. Guerrero, **J. Torres**, V. Creuze and A. Chemori, “Saturation based nonlinear PID control for underwater vehicles: Design, stability analysis and experiments”, *Mechatronics*, 61 (2019) 96–105
 34. J. Guerrero, **J. Torres**, V. Creuze and A. Chemori, “Observation-Based Nonlinear Proportional–Derivative Control for Robust Trajectory Tracking for Autonomous Underwater Vehicles”, *IEEE JOURNAL OF OCEANIC ENGINEERING*, DOI 10.1109/JOE.2019.2924561
 35. Marco Antonio Sánchez Mirafuentes, Julio Cesar Salas Torres, **Gabriel Villa Salvador**, Cogalois Theory and Drinfeld Modules, *Journal of Algebra and its Applications*, (2019) 10 de enero de 2019, 2050001-1-18.
 36. **Wen Yu** and Mario Lopez, Impact of random weights on nonlinear system identification using convolutional neural networks, *Information Sciences*, Vol.477, 1-14, 2019

37. Satyam Paul, **Wen Yu**, Xiaou Li, Discrete-time sliding mode for building structure bidirectional active vibration control, *Transactions of the Institute of Measurement and Control*, Vol.41, No.2, 433-1444, 2019.
38. R.Carreno, V.Aguilar, D.Pacheco, **W.Yu**, M.Elena, An IoT Expert System Shell in Block-Chain Technology with ELM as Inference Engine, *International Journal of Information Technology & Decision Making*, Vol. 18, No. 1, pp. 87-104, 2019
39. **Wen Yu** and Erick de la Rosa, Deep Boltzmann Machine for Nonlinear System Modelling, *International Journal of Machine Learning and Cybernetics*, Vol.10, No. 7, 1705--1716, 2019
40. J.Yang, T.Chai, C.Luo, **W.Yu**, Intelligent Demand Forecasting of Smelting Process Using Data-Driven and Mechanism Model, *IEEE Transactions on Industrial Electronics*, Vol.66, No.12, 9745-9755, 2019
41. R.Carreno, M.Acevedo Mosqueda, A.Mosqueda, F.Martinez, D.Pacheco and **W.Yu**, Computational Intelligence For Shoeprint Recognition, *Fractals*, Vol. 27, No. 4, 1-13, 2019
42. James Yu, **Wen Yu**, Jiatao Gu, Online vehicle routing with neural combinatorial optimization and deep reinforcement learning, *IEEE Transactions on Intelligent Transportation Systems*, Vol. 20, No. 10, 3806-3816, 2019
43. G. Puriel-Gil, **W.Yu**, and H.Sossa, Reinforcement Learning Compensation based PD Control for a Double Inverted Pendulum, *IEEE Latin America Trans.*, Vol.17, No.2, 323-330, 2019
44. Edgar Estrada, **Wen Yu**, Xiaou Li, Stability and transparency of delayed bilateral teleoperation with haptic feedback, *International Journal of Applied Mathematics and Computer Science*, Vol. 29, No. 4, 681-692, 2019.
45. Cesar U. Solis, Julio B. Clempner, **Alexander S. Poznyak**. Continuous-time gradient-like descent algorithm for constrained convex unknown functions: Penalty method application. *Journal of Computational and Applied Mathematics* 355 (2019) 268–282.
46. Kristal K. Trejo, Julio B. Clempner and **Alexander S. Poznyak**. Proximal constrained optimization approach with time Penalization. ENGINEERING OPTIMIZATION 2019, VOL. 51, NO. 7, 1207-1228, 2019
47. T.Poznyak, I. Chairez, **A. Poznyak**. Output-based modeling of catalytic ozonation by differential neuralnetworks with discontinuous learning law. *Process Safety and Environmental Protection*, 122 (2019) 83-93.
48. **A.Poznyak**. My friend Vadim I. Utkin (sketch on friendship and some photos fromprivate archives). *Int J Robust Nonlinear Control*. 2019; 29:522--528. DOI: 10.1002/rnc.4417
49. Erick Asiain · Julio B. Clempner · **Alexander S. Poznyak**. Controller exploitation-exploration reinforcement learning architecture for computing near-optimal policies. *Soft Computing* (2019) 23: 3591--3604.
50. Cesar U. Solis, Julio B. Clempner, **Alexander S. Poznyak**. Extremum seeking by a dynamic plant using mixed integral sliding mode controller with synchronous detection gradient estimation. *Int J Robust Nonlinear Control*. 2019; 29:702--714.
51. **A.Poznyak**, I. Chairez, T. Poznyak. A survey on artificial neural networks application for identification and control in environmental engineering: Biological and Chemical systems with uncertain models. *Annual Reviews in Control*, Volume 48, 2019, Pages 250-272, 2019
52. Bonifacio Sanchez, Carlos Cuvas, Patricio Ordaz, Omar Santos-Sánchez, and **Alexander Poznyak**. Full-Order Observer for a Class of Nonlinear Systems With Unmatched Uncertainties: Joint Attractive Ellipsoid and Sliding Mode Concepts. *IEEE TRANSACTIONS ON INDUSTRIAL ELECTRONICS.*, DOI: 10.1109/TIE.2019.2934066
53. Julio B. Clempner, **Alexander S. Poznyak**. Observer and control design in partially observable finite Markov chains. *Automatica*, Volume 110, December 2019, 108587. <https://doi.org/10.1016/j.automatica.2019.108587>.
54. **A.S.Poznyak**. Robust Identification under Correlated and Non-Gaussian Noises: WMLLM Procedure. ISSN 0005-1179, *Automation and Remote Control*, 2019, Vol. 80, No. 9, pp. 1628-1644
55. Kristal K. Trejo · Julio B. Clempner · **Alexander S. Poznyak**. Computing the Bargaining Approach for Equalizing the Ratios of Maximal Gains in Continuous-Time Markov Chains Games. *Computational Economics* (2019) 54: pp. 933--955.

56. C. U. Solis, J. B. Clempner & **A. S. Poznyak** , Robust integral sliding mode controller for optimisation of measurable cost functions with constraints, *International Journal of Control*, DOI:10.1080/00207179.2019.1662940
57. Rodrigo Castillo Gonzalez, Julio B. Clempner, **Alexander S. Poznyak**. Solving traffic queues at controlled-signalized intersections in continuous-time Markov games. *Mathematics and Computers in Simulation*. 166 (2019) 283--297.

b) Publicados en extenso en otras revistas especializadas, con arbitraje.

1. Jorge Morales, **Wen Yu**, Luciano Telesca, Bayesian Analysis of the Magnitude of Earthquakes Located in a Seismic Region of Italy, *MDPI Proceeding*, Vol.24(1), doi:10.3390/IECG2019-06214, 2019.
2. Jesús González, **Wen Yu**, Luciano Telesca, Earthquake Magnitude Prediction Using Recurrent Neural Networks, *MDPI Proceeding*, Vol. 24(22) doi:10.3390/IECG2019-06213, 2019.
3. Santos M. Orozco Soto, Alberto I. Pérez Sanpablo, Elisa Romero Ávila, Catherine Disselhorst Klug, **Juan M. Ibarra Zannatha**. Modelo neurodifuso para el control de un exoesqueleto para rehabilitación de brazo en pacientes con EVC, *Research in Computing Science*, 148(7), 2019
4. Oscar González Miranda, Santos, **JM. Ibarra Zannatha**. Potential field based control for autonomous vehicles using visual feedback, *Research in Computing Science* ,148(8), 2019

c) Publicados en extenso en memorias de congresos internacionales, con arbitraje.

IEEE Conference on Decision and Control (CDC19), Niza, Francia, 11 – 13 diciembre, 2019

1. Gian Carlo Gómez-Cortés, **Fernando Castaños** y Jorge Dávila; Sliding motions on $SO(3)$, sliding subgroups. pp. 6954 – 6958.
2. Pedro Flores-Palmeros, Pedro Castillo y **Fernando Castaños**; Backstepping-based controller for flight formation. pp. 254 – 260.
3. D. Bonilla Licea, **M. Bonilla**, M. Ghogho, M. Malabre. "UAV Trajectory Planning for Delay Tolerant Communications".

16th International Conference on Electrical Engineering, Computing Science and Automatic Control (CCE19), Mexico City, Mexico, 2019

4. Erick Asiain, **Rubén Garrido**. Servodrive chaotization: An MRCA approach using a nonlinear reference model.
5. Luis A. Cantera Cantera. Luis Luna. Cristóbal Vargas-Jarillo, **Rubén Garrido**. Parameter Estimation of a Linear Ultrasonic Motor Using the Least Squares of Orthogonal Distances Method.
6. Sina Razvarz, Raheleh Jafari, **Cristóbal Vargas-Jarillo** , Modelling and Analysis of Flow Rate and Pressure Head in Pipelines
7. Luis A. Cantera Cantera, Luis Luna, **Cristóbal Vargas-Jarillo**, Rubén Garrido , Parameter Estimation of a Linear Ultrasonic Motor Using the Least Squares of Orthogonal Distances Algorithm
8. L. Venegas and **J. Collado**. Relationship between a Damped Discrete Hill's Equation and an associated Undamped Discrete Hill's Equation
9. **Alejandro J. Malo Tamayo**, Diego R Peredo Ortiz y Abraham E, Rivera Ugalde, Rotary-Wing Aircraft Model for Control
10. PERRUSQUÍA, A; WEN, Y.; **SORIA, A.**- "Optimal contact force of Robots in Unknown Environments using Reinforcement Learning and Model-free controllers

11. Juarez, L., **Mondié, S.**, Vite, L., Nested stabilization for connected cruise control via the delay Lyapunov matrix
12. Cesar U. Solis, Julio B. Clempner and **Alexander S. Poznyak**. DC Motor Control based on Robust run-time Optimization Algorithm.
13. Jorge Ramirez, **Wen Yu**, Human Behavior Learning in Joint Space Using Dynamic Time Warping and Neural Networks,
14. Mario Maya, **Wen Yu**, Short-term prediction of the earthquake through Neural Networks and Meta-Learning,
15. Adolfo Perrusquia, Juan Alejandro, **Wen Yu**, Simple Optimal Tracking Control for a Class of Closed-Chain Mechanisms in Task Space,
16. Alexis Adrián Ortíz Olvera, **Juan Manuel Ibarra Zannatha**. Walk stability control for position-controlled servo actuated humanoid robot
17. Alberto Isaac Pérez Sanpablo, Catherine Disselhorst-Klug, Alicia Meneses-Peñaloza, Elisa Romero Avila, **Juan Manuel Ibarra Zannatha**, Josefina Gutiérrez Martínez and María Elena Arellano-Saldaña. Muscle Coordination of Elbow Joint During Low Resistance Movements in Healthy Children and Children with Cerebral Palsy

15th IFAC Workshop on Time Delay Systems Sinaia, Romania, September 9-11, 7-12, 2019

18. Adrián Ramírez, Rifat Sipahi, Sabine Mondié, **Rubén Garrido**. Fast Consensus in a Large-Scale Multi-Agent System with Directed Graphs Using Time-Delayed Measurements
19. Luis Juárez and **Sabine Mondié**, Dynamic Predictor-based Extended Cooperative Adaptive Cruise Control
20. Jorge-Manuel Ortega-Martínez, Omar-Jacobo Santos-Sánchez, **Sabine Mondié**, On the construction of the Bellman functional for time delay systems
21. Reynaldo Ortiz, **Sabine Mondié**, On the Lyapunov Matrix for Integral Delay Systems with a Class of General Kernel.

6th International Conference on Control, Decision and Information Technologies (CoDIT'19), Paris, France, 2019

22. Juarez, L., **Sabine Mondié**, Assisted cooperative adaptive cruise control with human memory effects
23. PERRUSQUÍA, A; **WEN, Y.**; **SORIA, A.**- "Large space dimension Reinforcement Learning for Robot Position/Force Discrete Control

10th International Conference on Intelligent Control and Information Processing (ICICIP 2019), Marrakesh, Morocco, 2019

24. Adolfo Perrusquia, **Wen Yu**, Xiaou Li, Impedance Control without Environment Model by Reinforcement Learning, 59-63
25. Erick Garcia, **Wen Yu**, Xiaou Li, Optimal Design of a Parallel Robot Using Neural Network and Genetic Algorithm, 64-69

2019 Global Medical Engineering Physics Exchanges/Pan American Health Care Exchanges (GMEPE / PAHCE). Buenos Aires, Argentina; March 26--31, 2019

26. E. Romero Ávila, A. I. Pérez Sanpablo, C. Disselhorst Klug, A. Meneses Peñaloza, M. E. Arellano Saldaña, J. Gutiérrez Martínez, **J. M. Ibarra Zannatha**. Influence of Increasing Joint Angle, Angular Velocity and External Load in the Extension Movement of the Elbow in Two Different Group Ages.
27. E. G. Cadena-Vilchis, A. I. Pérez Sanpablo, A. González-Mendoza, J. Gutiérrez-Martínez, I. Quiñones-Urióstegui, **J. M. Ibarra-Zannatha**, J. R. López-Gutiérrez. Electromechanical System for the Functional Evaluation of Muscular Activity during the Active Movement in the Elbow Joint

28. L.A. Blas, **M. Bonilla**, S. Salaza, M. Malabre, V. Azhmyakov. "Synthesis of a robust linear structural feedback linearization scheme for an experimental quadrotor, *18th European Control Conference (ECC)*, pp. 1431-1436, Napoli, Italy, June 25-28, 2019
29. Oscar B. Cieza, **Fernando Castaños** y Johann Regger; Implicit IDA-PBC for underactuated mechanical systems: An LMI-based approach; pp. 7770-7775, *International Conference on Unmanned Aircraft Systems*, Atlanta, EUA, 11-14 junio (2019)
30. V. Azhmyakov, **M. Bonilla**, S. Lahaye, N. Delanoue, L.A. Guzman Trujillo. "Application of the Projected Dynamics to Hybrid Systems and to the Sliding Mode Control Processes". *Proceedings of IFAC Advanced Control and Diagnosis - 15th ACD 2019*, 14 pp., Bologna, Italy, November 21-22, 2019.
31. Miguel Ramirez, **Joaquin Collado** and Faddi Donhal Stability of coupled and damped Mathieu equations utilizing symplectic properties. *International Nonlinear Dynamics Conference (NODYCON2019)*, Rome, Italy, 2019, 161, pp. 1-8
32. **Jesús Morales-Valdez**, Luis Alvarez-Icaza, José Alberto Escobar and Héctor Guerrero. Identification system for Structural Health Monitoring in Buildings. Pag. 31-38, *37th IMAC- A Conference and Exposition on Structural Dynamics 2019*, Orlando, USA
33. Juan Pablo Flores-Flores, **Rafael Martínez-Guerra**, A Dynamic Controller for PDE-based Systems, *2019 IEEE 7th International Conference Control Mechatronics and Automation*, Delft Netherland, Nov. 6-8, pp. 65-69,2019.
34. Raheleh Jafari, Sina Razvarz, **Cristóbal Vargas**, **Wen Yu**, Control of Flow Rate in Pipeline Using PID Controller, 16th IEEE International Conference on Networking, Sensing, and Control (ICNSC19), Banff, Canada, 293-298, 2019
35. Raheleh Jafari, Sina Razvarz, **Cristóbal Vargas-Jarillo**, Alexander Gegov, The Effect of Baffles on Heat Transfer, *16th International Conference on Informatics in Control, Automation and Robotics (ICINCO 2019)*; ISBN: 978-989-758-380-3
36. Sina Razvarz, **Cristóbal Vargas-Jarillo**, Raheleh Jafari, Pipeline Monitoring Architecture based on observability and controlability Analysis, *IEEE International Conference on Mechatronics (ICM) 2019*, ISBN: 978-1-5386-6959-4
37. OJEDA MISSES, M. ; BARUCH I., **SORIA LÓPEZ, A.**, "A real-time identification for hand-based movements using Recurrent Complex-Valued Neural Networks", *2019 IEEE 4th Colombian Conference on Automatic Control (CCAC)*. DOI: 10.1109/CCAC.2019.8920864
38. **Alex S. Poznyak**. Extremum Seeking for Second Order Uncertain Dynamic Plant. *Preprints of the 27th Mediterranean Conference on Control and Automation (med19)*, Akko, Israel, July 1-4, 2019, pp. 559-564
39. Ballesteros, M., Polyakov, A., Efimov, D., Chairez, I., & **Poznyak, A.** (2019). Differential Neural Network Identification for Homogeneous Dynamical Systems. *11th IFAC Symposium on Nonlinear Control Systems NOLCOS 2019*: Vienna, Austria, 4-6 September 2019
40. Adolfo Perrusquia, **Wen Yu**, Task space human-robot interaction using angular velocity Jacobian, *2019 International Symposium on Medical Robotics (ISMR19)*, Atlanta, USA, 1-6, 2019.
41. **Wen Yu**, Xiaou Li, Jesus Gonzalez, Fast training of deep LSTM networks, *16th International Symposium on Neural Networks (ISNN 2019)*, Moscow, Russia, Springer LNCS 11554, 3-10, 2019
42. **Jesus Morales**, Mario Antonio, **Wen Yu**, Damage detection of building structure based on vibration data and hysteretic model, *15th IEEE International Conference on Automation Science and Engineering (CASE 2019)*, Vancouver, Canada, 608-613, 2019
43. Salvador Ortiz, **Wen Yu**, XiaouLi, Autonomous navigation in unknown environments using robust SLAM, *45th Annual Conference of the IEEE Industrial Electronics Society (IECON19)*, Lisbon, Portugal, 5450-5455, 2019

44. **Wen Yu**, America Morales, Data driven fast real-time optimization with application to crude oil blending, *1st International Conference on Industrial Artificial Intelligence*, DOI: 10.1109/ICIAI.2019.8850833, Shenyang, China, 2019
45. Alexis A. Ortiz Olvera, Santos Miguel Orozco Soto, **Juan Manuel Ibarra Zannatha**. ADRC controller for weightlifter Humanoid robot. *The 29th International Conference on Electronics, Communications and Computers*, Cholula, Pue. Febrero 2019 DOI: 10.1109/CONIELECOMP.2019.8673147
46. Romero-Avila E, Pérez-Sanpablo AI, Disselhorst-Klug C, Meneses-Peñaloza A, Arellano-Saldaña ME, Gutierrez-Martinez J, **Ibarra-Zannatha JM**, Clinical and kinematic evaluation of the Upper Limbs in Children with Cerebral Palsy, *International Neurorehabilitation Symposium (INRS) 2019*, Rehabweek, 24--28 June 2019, Toronto, Canada
47. Romero-Avila E, Pérez-Sanpablo AI, Disselhorst-Klug C, Meneses-Peñaloza A, Arellano-Saldaña ME, Gutierrez-Martinez J, **Ibarra-Zannatha JM**, Effect of different external loads during the extension movement of the elbow on muscular activity in children and adults. *XXVII Congress of the International Society of Biomechanics (ISB2019) and 43rd Annual Meeting of the American Society of Biomechanics (ASB2019)*. Calgary, Canada; July 31-August, 2019
48. Alberto Isaac Pérez Sanpablo, Catherine Disselhorst-Klug, Alicia Meneses-Peñaloza, Elisa Romero Ávila, **Juan Manuel Ibarra Zannatha**, Josefina Gutiérrez Martínez and Gerardo Rodríguez Reyes. Analysis of Joint Position and Joint Velocity influence over Muscle Activity of Elbow Joint in Normal and Pathologic Children. *CLAIB 2019 - VIII Congreso Latinoamericano de Ingeniería Biomédica*. Cancún, QR, México. 2-5 Octubre 2019

d) **Publicados en extenso en memorias de congresos locales, con arbitraje.**

Congreso Nacional de Control Automático, Puebla, Puebla, 23-25 octubre, 2019

- 1 Gian Carlo Gómez-Cortés, **Fernando Castaños** y Jorge Dávila; Control en la esfera S2 usando modos deslizantes. pp. 778 – 784;
- 2 **Rubén Garrido**, Eric Asiain. Caotización de un servomecanismo de CD mediante un controlador adaptable utilizando un modelo de referencia no lineal. 594-599.
- 3 Juan Pablo Flores-Flores, **Rafael Martínez-Guerra**, "Sincronización de sistemas descritos por ecuaciones diferenciales parciales mediante un controlador dinámico. 743-748
- 4 **Jesús Morales-Valdez**, Mario Antonio López Pacheco, **Wen Yu**. (2019). Detección de daño en edificios basada en datos de aceleración y redes neuronales convolucionales. 145-150.

CoMRob 2019, XXI Congreso Nacional de Robótica de la AMRob, Manzanillo, Col., 13 - 15 noviembre de 2019.

- 5 A.D. Hernández Rojas, **J.M. Ibarra Zannatha**, J. Cantillo-Negrete. Development of a Vision-Assisted Robotic Manipulation System
- 6 Santos M. Orozco Soto, **J.M. Ibarra Zannatha**. N. González Dorantes, M. L. Ramos Andrés, J.M. Ibarra Zannatha, M. Villafuerte Bante, P. Vera Bustamante. Task-Space Control of Robot Manipulator using Robust Visual Estimation.
- 7 Eleazar Rivera Morales, Daniel Lechuga Rosales, Pablo Vera Bustamante, Mario Villafuerte Bante, **Juan Manuel Ibarra Zannatha**. Autonomous Vehicle's Instrumentation.
- 8 Oscar González Miranda, Santos Miguel Orozco Soto, Juan Manuel Ibarra Zannatha. Potential field-based preview control of an autonomous vehicle using visual feedback.

- 9 Miguel Ramirez, **Joaquin Collado** and Faddi Donhal. Transient vibrations suppression in parametrically excited resonators. *Latin American Symposium on Industrial and Robotic Systems*, Tampico Mexico 2019, pp. 1-6

5.1.2. Artículos de revisión en libros publicados por una casa editorial reconocida o revista de circulación internacional.

5.1.3. Capítulos de investigación original en extenso en libros especializados publicados por una casa editorial.

1. Miguel Ramirez, **M. Joaquin Collado** and Faddi Donhal. “Coupled Mathieu Equations: γ -Hamiltonian and μ -Symplectic”, 2019, IntechOpen, https DOI: <http://dx.doi.org/10.5772/intechopen.88635>, pp. 1-22.
2. Carlos Cuvas, Adrián Ramírez, Luis Juárez, **Sabine Mondié**, Scanning the Space of Parameters for Stability Regions of a Class of Time-Delay Systems; A Lyapunov Matrix Approach, IN: Delays and Interconnections: Methodology, Algorithms and Applications, *Advances in Delays and Dynamics*, vol 10. Springer, 153-167, 2019.
3. Daniel Carrillo and **Wen Yu**, Hierarchical Dynamic Neural Networks for Cascade System Modeling with Application to Wastewater Treatment, Alma Alanis, Nancy Arana and Carlos López (Eds.), *Artificial Neural Networks for Engineering Applications*, 1-8, Academic Press, 2019.
4. Carlos Parga and **Wen Yu**, Design and Modeling of Shoulder Exoskeleton Using Two Spherical Joints, Jacob Rosen and Peter Ferguson (Eds.), *Wearable Robotics*, 133-148, Academic Press, 2019.
5. **Juan Manuel Ibarra Zannatha**. Los Avances de la Robótica Médica en México, *Desarrollo Industrial 2050. Hacia una industria del futuro*. UNAM 2019

5.1.4. Libros especializados que cubran el trabajo del investigador, publicados por una casa editorial reconocida.

1. **Wen Yu** and Raheleh Jafari, *Modeling and Control of Uncertain Nonlinear Systems with Fuzzy Equations and Z-Number*, Wiley, 2019.
2. **Rafael Martínez-Guerra**, Oscar Martínez-Fuentes, Juan Javier Montesinos-García, *Algebraic and Differential Methods for Nonlinear Control Theory: Elements of Commutative Algebra and Algebraic Geometry*, Springer, 2019.
3. Tatyana I. Poznyak, Isaac Chairez Oria, **Alexander S. Poznyak** *Ozonation and Biodegradation in Environmental Engineering: Dynamic Neural Network Approach*. Elsevier, 2019.

5.2 PRODUCTOS DE DESARROLLO

5.2.2. Patentes Otorgadas

c) Nacionales en explotación comercial

Arellano Saldaña ME, Disselhorst-Klug C, Gutiérrez-Martínez J, **Ibarra Zannatha JM**, Pérez Sanpablo AI, Quiñones Uriostegui I, Rodríguez Reyes G, Romero-Ávila E. Base de datos con valores de referencia de velocidad articular y actividad muscular de miembro superior de sujetos pediátricos sanos y con parálisis cerebral. Compilación de Datos (Base de Datos). *INDAUTOR. 03-2019-071510550200-01*

5.2.6. Divulgación Científica

d) Reseña de artículos

- a. **León, J.A.** Reseña de: Multiscale systems, homogenization, and rough paths. *Probability and analysis in interacting physical systems*. Springer Proc. Math. Stat. (2019), **283**: 17–48pp, de I. Chevryrev; P.K. Friz; A. Korepanov; I. Melbourne; H. Zhang. En: Mathematical Reviews (2019-11-26). Número de reseña: **MR3968507**.
- b. **León, J.A.** Reseña de: A Stratonovich-Skorohod integral formula for Gaussian rough paths. *Ann. Probab.* (2019), **47** no. 1: 1–60pp, de T. Cass; N. Lim. En: Mathematical Reviews (2019-07-19). Número de reseña: **MR3909965**.
- c. **León, J.A.** Reseña de: Module free white noise flows. *Open Syst. Inf. Dyn.* (2018), **25**, no. 4, 1850018: 34pp, de W. Ayed. Mathematical Reviews (2019-08-02). Número de reseña: **MR3918071**.
- d. **León, J.A.** Reseña de: Strong solutions of mean-field stochastic differential equations with irregular drift. *Electron. J. Probab.* (2018), **23**, paper 132: 35pp, de M. Bauer, T. Meyer-Brandis, F. Prosk. En: Mathematical Reviews (2019-06-11). Número de reseña: **MR3896869**.
- e. **León, J.A.** Reseña de: Stochastic evolution equations with Wick-polynomial nonlinearities. *Electron. J. Probab.* (2018), **23**, paper 116: 25pp, de T. Levajković; S. Pilipović; D. Seleši; M. Žigić. En: Mathematical Reviews (2019-09-13). Número de reseña: **MR3885549**.
- f. **León, J.A.** Reseña de: Weak differentiability of Wiener functionals and occupation times. *Bull. Sci. Math.* (2018), **149**: 23-65pp, de D. Leão; A. Ohashi; A.B. Simas. En: Mathematical Reviews (2019-04-08). Número de reseña: **MR3868115**.
- g. **León, J.A.** Reseña de: Kolmogorov equations and weak order analysis for SPDEs with nonlinear diffusion coefficient. *J. Math. Pures Appl.* (2018), **119**: 193-254pp, de C.-E. Bréhier; A. Debussche. En: Mathematical Reviews (2019-03-01). Número de reseña: **MR3862147**.
- i. **León, J.A.** Reseña de: Stochastic Burgers' equation on the real line: regularity and moment estimates. *Stochastics* (2018), **90**: 1053-1086pp, de P. Lewis; D. Nualart. En: Mathematical Reviews (2019-03-06). Número de reseña: **MR3854527**.
- j. **León, J.A.** Reseña de: Gradient estimates for SDEs without monotonicity type conditions. *J. Differential Equations* (2018), **265**: 1984-2012pp, de G. Da Prato; E. Priola. En: Mathematical Reviews (2019-01-17). Número de reseña: **MR3800108**.

Martha Rzedowski Calderon

- a. Reseñas para la AMS (American Mathematical Association):
- b. Marzo 2019 (3 885 142) Chuang,Wei;2019-05-07)
- c. Julio 2019 (3 947 643) König,Legrand,Neftin;2019-09-08)
- d. Octubre 2019 (3 990 961) Harbater, Hartmann,Krashen,Parimala,Raman;)

Gabriel Villa Salvador

- a. Mathematical Reviews (American Mathematical Society):3846350 Lüdtkke, Martini (11 de junio de 2019) (MR3846350)
- b. Reseña del Artículo: MR3846350 Lüdtkke, Marti, *A birational anabelian reconstruction theorem for curves over algebraically closed fields in arbitrary characteristic*, Israel J. Math. **227** (2018), no. 2, 987–1011. 3861043 Greither, Cornelius; Popescu, Cristian D. (17 de noviembre de 2018) (MR3861043)

- c. Reseña del Artículo: MR3861043 Greither, Cornelius; Popescu, Cristian D., *Abstract l -adic π -motives and Tate's canonical class for number fields*, Doc. Math. **23** (2018), 839–870.3880299 Jacinto, Joaquín Rodrigues (19 de febrero de 2019) (MR3880299)
- d. Reseña del Artículo: MR3880299 Jacinto, Joaquín Rodrigues, *La conjecture \square locale de Kato en dimension 2*, Math. Ann. **372** (2018), no. 3–4, 1277–1334.3959855 Thorne, Jack A. (6 de agosto de 2019) (MR3959855)
- e. Reseña del Artículo: MR3959855 Thorne, Jack A., *Elliptic curves over \mathbb{Q}_{∞} are modular*, J. Eur. Math. Soc. (JEMS) **21** (2019), no. 7, 1943–1948. Zentralblatt für Mathematik/Mathematics Abstracts, DEB18814 Oswald, Nicola; Steuding, Jörg (19 de septiembre de 2018) (Zbl 1413.11107)
- f. Reseña del Artículo: Zbl 1413.11107 Oswald, Nicola; Steuding, Jörg, *A uniqueness theorem for entire functions having a Dirichlet series representation*, Ann. Univ. Sci. Budap. Rolando Eötvös, Sect. Comput. **48**, 117–128 (2018). DE065997782 Anglès, Bruno; Ngo Dac, Tuan; Tavares Ribeiro, Floric (16 de octubre de 2018) (Zbl 1401.11127)
- g. Reseña del Artículo: Zbl 1401.11127 Anglès, Bruno; Ngo Dac, Tuan; Tavares Ribeiro, Floric, *Twisted characteristic p zeta functions*, J. Number Theory **168**, 180–214 (2016). DE063774536 Lagemann, Thorsten (18 de octubre de 2018) (Zbl 1401.11150)
- h. Reseña del Artículo: Zbl 1401.11150 Lagemann, Thorsten, *Distribution of Artin–Schreier–Witt extensions*, J. Number Theory **148**, 288–310 (2015). DE069284031 Roquette, Peter (3 de enero de 2019) (Zbl 1414.11003)
- i. Reseña del Libro: Zbl 1414.11003 Roquette, Peter, *The Riemann hypothesis in characteristic p in historical perspective*, Lecture Notes in Mathematics **2222**. History of Mathematics Subseries. Cham: Springer (ISBN 978-3-319-99066-8/pbk; 978-3-319-99067-5/ebook). ix, 233 p. (2018).DE070236494 Chang, Chieh-Yu; Papanikolas, Matthew A.; Yu, Jing (6 de marzo de 2019) (Zbl 1417.11139)
- j. Reseña del Artículo: Zbl 1417.11139 Chang, Chieh-Yu; Papanikolas, Matthew A.; Yu, Jing, *An effective criterion for Eulerian multizeta values in positive characteristic*, J. Eur. Math. Soc. (JEMS) **21**, No. 2, 405–440 (2019). DEB19287 Azizi, A.; Jerrari, I.; Talbi, M. (12 de abril de 2018) (Zbl 07058283)
- k. Reseña del Artículo: Zbl 07058283 Azizi, A.; Jerrari, I.; Talbi, M., *On the rank of the 2-class group of an extension of degree 8 over \mathbb{Q}* , Period. Math. Hung. **78**, No. 1, 128–134 (2019). DE070705252 Bank, Efrat; Foster, Tyler (27 de junio de 2019) (Zbl 07070525)
- l. Reseña del Artículo: Zbl 07070525 Bank, Efrat; Foster, Tyler, *Primes in short intervals on curves over finite fields*, Math. Ann. **374**, No. 1–2, 447–474 (2019). DE070365446 Platonov, V. P.; Zhgoon, V. S.; Petrunin, M. M.; Shteinikov, Yu. N. (20 de junio de 2019) (Zbl 07036544)
- m. Reseña del Artículo: Zbl 07036544 Platonov, V. P.; Zhgoon, V. S.; Petrunin, M. M.; Shteinikov, Yu. N., *On the finiteness of hyperelliptic fields with special properties and periodic expansion of $\sqrt[n]{f}$* , Dokl. Math. **98**, No. 3, 641–645 (2018); translation from Dokl. Akad. Nauk, Ross. Akad. Nauk **483**, No. 6, 603–608 (2018).DE070736965 Mazhouda, Kamel; Smajlović, Lejla (28 de junio de 2019) (Zbl 07073696)
- n. Reseña del Artículo: Zbl 07073696 Mazhouda, Kamel; Smajlović, Lejla, *Evaluation of the Li coefficients on function fields and applications*, Eur. J. Math. **5**, No. 2, 540–550 (2019). DE070057715 Ma, Liming; Xing, Chaoping (2 de agosto de 2019) (Zbl 07005771)
- o. Reseña del Artículo: Zbl 07005771 Ma, Liming; Xing, Chaoping, *On subfields of the Hermitian function field involving the involution automorphism*, J. Number Theory **198**, 293–317 (2019). DE070507926 Doyle, John R. (20 de septiembre de 2018) (Zbl 07050792)
- p. Reseña del Artículo: Zbl 07050792 Doyle, John R., *Dynamical modular curves for quadratic polynomial maps*, Trans. Am. Math. Soc. **371**, No. 8, 5655–5685 (2019).DE070817947 Dan, Ananyo; Kaur, Inder (10 de septiembre de 2019) (Zbl 07081794)
- q. Reseña del Artículo: Zbl 07081794 Dan, Ananyo; Kaur, Inder, *Examples of varieties*

1. ESTUDIANTES GRADUADOS

1.1. MAESTRÍA

1. JAVIER EDUARDO PEREYRA ZAMUDIO
TESIS: Nuevo diseño de backstepping con retardos artificiales para sistemas con retardos puntuales
GRADO OBTENIDO: Maestría
DIRECTOR DE TESIS: **SABINE MONDIE CUZANGE**
FECHA: 29/08/2019
2. Jorge Ramirez
Título de tesis: Aprendizaje de comportamiento humano en espacio articular del robot utilizando redes neuronales
Especialidad: Control Automático
Director de tesis: **Dr. Wen Yu**
Fecha de obtención de grado: 12/08/2019
3. Luis Guillermo Venegas Pineda
Título de tesis: Ecuación de Hill discreta sin y con amortiguamiento
Especialidad: Control Automático
Director de tesis: **Dr. Joaquín Collado Moctezuma**
Fecha de obtención de grado: 12/09/2019
4. Aline Iobana Acevedo Velazquez
Título de tesis: Control de sistemas bilineales en malla abierta
Especialidad: Control Automático
Director de tesis: **Dr. Joaquín Collado Moctezuma**
Fecha de obtención de grado: 24/09/2019
5. Olga Lidia Jiménez Morales
TESIS: Estudio comparativo de motores de CD orientados a la construcción de prototipos de bajo costo.
GRADO OBTENIDO: Maestría
DIRECTOR DE TESIS: **Rubén Alejandro Garrido Moctezuma.**
FECHA: 30/08/2019.
6. Oscar González Miranda.
TESIS: Modelado y Control de un vehículo autónomo.
GRADO OBTENIDO: Maestría
DIRECTOR DE TESIS: **Juan Manuel Ibarra Zannatha.**
FECHA: 17/12/2019.

1.2. DOCTORADO

1. SINA RAZVARZ
TESIS: Modelado, Simulación y Detección de Fallas en una Red de Tuberías
GRADO OBTENIDO: Doctorado en la Especialidad de Control Automático
DIRECTOR DE TESIS: **Cristóbal Vargas Jarillo**
FECHA: 27 de agosto de 2019.
2. ELIZABETH RAMÍREZ RAMÍREZ

TESIS: Campos de géneros extendidos de campos globales y extensiones abelianas imaginarias con número de clases de ideales uno.

GRADO OBTENIDO: Doctorado

DIRECTOR DE TESIS: **Martha Rzedowski Calderon**

FECHA: 26 de abril de 2019.

3. Salvado Ortiz
Título de tesis: Localización y mapeo simultáneo robusto aplicado a la planeación de trayectorias en robot móviles
Especialidad: Control Automático
Director de tesis: **Dr. Wen Yu**
Fecha de obtención de grado: 10/02/2019
4. Jesús González
Título de tesis: Modelado de sistemas dinámicos usando redes neuronales recurrentes profundas
Especialidad: Control Automático
Director de tesis: **Dr. Wen Yu**
Fecha de obtención de grado: 13/12/2019
5. Marco Antonio Ortiz Castillo
Título de tesis: "Representaciones implícitas de sistemas conmutados: Aplicaciones al diseño LQR".
Especialidad: Control Automático
Director de tesis: **Dr. Moisés Bonilla Estrada**
Fecha de obtención de grado: 06/12/2019
6. Oscar Martinez Fuentes
Tesis: Observadores Mittag-Leffler para Sistemas Fraccionarios
Especialidad: Control Automático
Director de Tesis: **Rafael Martínez-Guerra**
Fecha de Obtencion: 16 Agos/2019
7. Juan Javier Montesinos Garcia
Tesis: Comunicaciones Seguras en Sistemas Fraccionales
Especialidad: Control Automático
Director de Tesis: **Rafael Martínez-Guerra**
Fecha de Obtencion: 16 Agos/2019.
8. Cesar Ulices Solis
Tesis: Extremum seeking by a dynamic plant using mixed integral sliding mode controller with synchronous detection gradient estimation
Especialidad: Control Automático
Director de Tesis: **Dr. Alexander Pozniak Gorbach**
Fecha de Obtencion: 06 de diciembre de 2019.

2. PREMIOS Y DISTINCIONES

3. PARTICIPACIÓN EN COMISIONES DE EVALUACIÓN, COMITÉS TÉCNICOS Y COMITÉS EDITORIALES DE REVISTAS

1. Fernando Castaños Luna

IFAC Technical Committee "Nonlinear Systems",
Associate Editor International Journal of Robust and Nonlinear Control,
Program Committee CNCA 2019,

- Program Committee CCE 2019.
2. **Jorge Alberto León Vázquez**
Comité Editorial de *Aportaciones Matemáticas de la Sociedad Matemática Mexicana*.
 3. **Jorge Alberto León Vázquez**
Comité Editorial de *Mixba'al. Revista Metropolitana de Matemáticas*.
 4. **Martha Rzedowski Calderón**
Coordinadora del Área de Teoría de Números del **52 Congreso de la Sociedad Matemática Mexicana de marzo a octubre de 2019**.
Lugar: Universidad Autónoma de Nuevo León
 5. Miembro de la Comisión Dictaminadora del área VII del SNI, 2019; **Sabine Mondié**.
Vice chair of the IFAC Technical Committee of Linear systems; **Sabine Mondié**.
 6. **Wiederhold Petra**: Miembro del Comité del Programa y Revisor de 3 artículos para ICIEV&IVPR 2019
(Joint 8th Int. Conf. on Informatics, Electronics & Vision (ICIEV) & 3rd Int. Conf. on Imaging, Vision & Pattern Recognition (IVPR), April 2019, Washington, USA), reviewing period: Jan. 2019.
Revisor para la revista *Annals of Mathematics and Artificial Intelligence (AMAI, Springer)*, reviewing period: Aug. 2019.
Revisor para *Journal of Theoretical Computer Science* (Elsevier), reviewing period: Nov. 2019.
Revisor para *FILOMAT journal of pure and applied mathematics* (ISSN: 2406-0933, Faculty of Sciences and Mathematics, University of Nis, Republic of Serbia), reviewing period: Nov.-Dec. 2019
 7. **Alexander Ponzniak**: Comité de evaluación SNI: sección Eméritos 2019-2020.
- He is Fellow of IMA (Institute of Mathematics and Its Applications, Essex UK)
- Associated Editor of
 - Oxford-IMA **Journal on Mathematical Control and Information**,
 - **Kybernetika** (Czech Republic),
 - **Nonlinear Analysis: Hybrid systems** (IFAC).
 8. Revisor para las revistas internacionales en el 2019: **Rafael Martínez Guerra**
 - INTERNATIONAL JOURNAL ROBUST AND NONLINEAR CONTROL
 - INTERNATIONAL JOURNAL OF THE FRANKLIN INSTITUTE
 - AUTOMATICA
 - JOURNAL OF APPLIED MATHEMATICS
 - CONFERENCE ON DECISION AND CONTROL (CDC), 2019.
 - AMERICAN CONTROL CONFERENCE (ACC), 2019.
 - CCE, 2019.
 - AMCA 2019.
 - ICCMA 2019.
 9. **Jesús Morales Valdez**
 - Program Chair - CCE 2019
 - Revisor para la revista IEEE Latin American Transaction,
 - Revisor para la revista International Journal of Dynamics and Control
 - Revisor para la revista IEEE Transactions on Automation Science and Engineering
 10. **J. M. Ibarra Zannatha**
 - Member of the Editorial Board of the Springer Series on Touch and Haptic Systems.
 - Member of the Advisory Board of the AMRob Journal, Robotics: Theory and Applications.
 - Revisor de las revistas siguientes:
 - IEEE Transactions on Mechatronics
 - Robotics and Autonomous Systems, Elsevier
 - Computer Methods and Programs in Biomedicine, Elsevier
 - Mathematical Problems in Engineering, Hindawi Publishing Corporation
 - Comité Editorial de la Revista Ingeniería y Desarrollo, Colombia
 - Evaluador de Proyectos de Investigación (CONICET, Argentina)
 -
 - Evaluador de Proyectos de Investigación para la Fundación para la Educación y el Desarrollo

Social (FES) Colombia. Proyectos evaluados durante 2018:

- Desarrollo y evaluación de un sistema multispectral para el diagnóstico y monitoreo de cultivo de aguacate Hass
- Corrección y calibración de imágenes multispectrales e hiperespectrales capturadas desde plataformas aéreas en un ambiente tropical andino
- Caracterización de aguacate Hass para monitoreo de cambios fisiológicos, producción, calidad y diagnóstico de plagas y enfermedades usando firmas espectrales
- Desarrollo de plataformas aéreas para aplicaciones de percepción remota en un ambiente tropical andino.

1. PROYECTOS FINANCIADOS POR AGENCIAS NACIONALES O INTERNACIONALES DE APOYO A LA CIENCIA (CONACYT, COSNET, FUNDACIÓN ROCKEFELLER, ETC.)

1. Título: “Control e implementación de un sistema fotovoltaico de alta concentración”.
Clave del proyecto: CONACyT 222140.
Vigencia: Marzo 2015-Marzo 2019.
Responsable : **Rubén Alejandro Garrido Moctezuma**
Participantes: Dr. Arturo Díaz, Dr. Juan José Soto Bernal, M. en C. Kevin López, Ing. Yves Pérez.
Fuente: Proyectos Ciencia Básica SEP-CONACyT
Monto: \$ 1,326,578.00 pesos
2. Proyecto: “Matriz de Lyapunov para sistemas con retardos y sus aplicaciones”
Clave: A1-S-24796
Vigencia: Noviembre 2019 a Noviembre 2021.
Responsable: **Dra. Sabine Mondié Cuzange**
Participantes: Dr. Omar Santos, Dr. Alexey Egorov, Dr. Liliam Rodriguez, Dr. Marco Antonio Gomez, M. en C. Luis Juarez, M. En C. Reynaldo
Fuente de financiamiento: Fondo Sectorial SEP-Conacyt de Investigación básica
Monto: \$ 1,261,648.00 Pesos
3. Proyecto: “Matriz de Lyapunov para sistemas con retardos”
Clave: 155
Vigencia: marzo 2019 a marzo 2021.
Responsable: **Dra. Sabine Mondié Cuzange**
Participantes: Dr. Rubén Garrido Moctezuma, Dr. Alexey Egorov, M. En C. Kevin Lopez Preciado, M. en C. Luis Juarez,
Fuente de financiamiento: Fondo SEP-CINVESTAV
Monto: \$ 300,000.00 Pesos
4. Título: Modeling and Control for Human-Robot Interaction with Deep Reinforcement Learning
Responsable: **Wen Yu**
Agencia de financiamiento: CONACyT-A1-S-8216
Tipo de proyecto: Investigación
Monto: \$ 1,927,000.00 pesos
Vigencia: Noviembre 2019- Noviembre 2022.
5. Título: Development of machine learning-based innovative methods of seismic forecasting in Italy and Mexico
Responsable: **Wen Yu**

- Agencia de financiamiento: CNR (Consejo Nacional de Investigación Italiano)
Tipo de proyecto: Investigación
Monto: \$ 1,050,000.00 pesos
Vigencia: Marzo 2019- Marzo 2021.
6. Titulo: Semi-Active Control of Building Structures Based on Structure Health Monitoring and Deep Learning Techniques
Responsable: **Wen Yu**
Agencia de financiamiento: SEP-CINVESTAV
Tipo de proyecto: Investigación
Monto: \$ 250,000.00 pesos
Vigencia: Mayo 2019- Mayo 2021.
7. Numero: 251552
Área: Ciencias de la Ingeniería.
Titulo: Desarrollo de Sistema de Estabilización y Orientación para Satélites Atados en Base de Modos Deslizantes Adaptables.
Vigencia: julio 2016 - marzo 2020.
Responsable: **ALEXANDER SEMION POZNIAK GORBATCH**
Fuente: SEP-CONACyT
Monto: \$ 1,470,000.00 pesos
8. Proyecto: SMARTMOVE (Smart orthotic device to improve movement capacity of patients suffering from spasticity)
Programa: Fonciycyt (proyecto No. 267734)
Instituciones Participantes: RWTH Aachen University (Dra. C. Disselhorst Klug)
Instituto Nacional de Rehabilitación (Dra. Josefina Gutiérrez)
Cinvestav
Responsable: **Juan Manuel Ibarra Zannatha**
Vigencia: enero 2017 – diciembre 2019
Monto: \$ 2,700,000.00

2. DIRECCIÓN POSTAL Y ELECTRÓNICA

Dr. Wen Yu Liu

Jefe del Departamento de Control Automático

Ma. Elizabeth León Meza

Asistente secretarial de la Jefatura

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07360 México, DF, México
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Dr. Moisés Bonilla Estrada

Coordinador Académico del Departamento de Control Automático

Catalina Montelongo Ávila

Secretaria de Coordinación Académica

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