



Personal information

Surname(s) / First name(s)

Castaños Luna Fernando

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Nationality(-ies)

Mexican

Date of birth

1976

Research interests

Nonlinear control, Hamiltonian systems, implicit systems, neuromorphic engineering, passivity-based control, robust control and variable structure systems

Education

2006 – 2009

PhD Degree: Physics, Control Theory. Supervised by Romeo Ortega

Thesis: Cyclo-passivity and control by interconnection

Université Paris-Sud XI (UPS) – Laboratoire des signaux et systèmes (L2S) – SUPÉLEC, France

2005 – 2006

Master Degree: Control and Signal & Image Processing. Supervised by Romeo Ortega

Internship: Collaboration in a project dedicated to develop passivity-based control laws. L2S

UPS – L2S – SUPÉLEC

2003 – 2004

Master Degree: Electric Engineering, Automatic Control. Supervised by Leonid Fridman

Thesis: Sliding-modes with an \mathcal{H}_∞ criterion and application to decentralized control

Universidad Nacional Autónoma de México (UNAM). Mexico

1995 – 2002

Bachelors' Degree: Electric & Electronic Engineering, Signal Processing. Supervised by Rolando Carrera

Thesis: Swing-up and stabilization of an inverted pendulum. Engineering Faculty, UNAM

Internship: Collaboration in a project dedicated to detect and estimate leaks by using observers. Engineering Institute, UNAM

Professional experience

Mar. 2019 –

Positions

Editor of the International Journal of Robust and Nonlinear Control, Wiley

Mar. 2014 –

Researcher. Automatic Control Department (DCA). Centro de Investigación y de Estudios Avanzados del IPN (Cinvestav), Mexico. Level 3C. Academic Dean from April 2015 to March 2017

Sep. 2011 – Feb. 2014

Visiting researcher. DCA, Cinvestav

Sep. 2009 – Aug. 2011

Post-doctoral fellow. McGill Center for Intelligent Machines, McGill University, Canada. Locomotion control of humanoid robots. Supervised by Hannah Michalska and Vincent Hayward

2001 – 2002	Freelancer. Computer networks implementation. Design and implementation of web sites
1998 – 2000	Consultant at SSE-México. Design and implementation of financial models in computer systems. Development of the interfaces between the transactional systems. Development of the user interfaces
	<i>Scientific visits</i>
2018, 2015	Dmitry Gromov. Implicit port-Hamiltonian systems. Saint Petersburg State University, St. Petersburg, Russia. Two weeks, one week, respectively
2017	Emmanuel Nuño. Passivity-based control using multifunctions. University of Guadalajara, Guadalajara, Mexico. One week
2014	Alessio Franci. Realisation of complex nonlinear behaviours using singularity theory. Department of Engineering, University of Cambridge, UK. One week
2012, 2013	Cristian Kunusch. Minimization of hydrogen consumption in fuel cells. Institut de Robòtica i Informàtica Industrial. Barcelona, Spain. Two weeks, one week, respectively
2009	Riyanto Bambang. Power control of electric vehicles. Institute of Technology Bandung. Bandung, Indonesia. Two weeks
2008	David Hill and Jun Zhao. Control applications of dissipativity theory for switched circuits. Australian National University. Canberra, Australia. Four weeks
	Bayu Jayawardhana, Arjan van der Schaft and Jacquélien Scherpen. Power-based models for circuit theory, energy-shaping of port-Hamiltonian systems. University of Groningen. The Netherlands. One week
2007	Ravi Banavar and Arun Mahindrakar. Control by interconnection in the infinite-dimensional case. Indian Institute of Technology. Mumbai and Chennai, India. Four weeks
2006	Jacquélien Scherpen and Dimitri Jeltsema. Relative passivity applied to power converters. Delft University of Technology. Delft, The Netherlands. One week
	Arjan van der Schaft. Switched Hamiltonian systems. Systems University of Groningen. One week
	<i>Projects</i>
2009	Power flow control of fuel-cell powered vehicles (author). NUSANTARA, budget € 5,000
2008	Transient Stability of Power Systems. FAST, budget € 6,800
2006	Control of Active Filters considering Dynamic Loads. LAFMAA, budget € 13,950
	<i>Courses taught</i>
	<i>Cinvestav, graduate level:</i>
Jan. – Apr. 2020	Robust Control
May. – Aug. 2019, 2018	
Sep. – Dec. 2019	Homogeneous Systems and Systems with Delays
May. – Aug. 2017	Sliding-mode Control
Jan. – Apr. 2017, 2016	Optimal Control
2015, 2014	
May. – Aug. 2016, 2015	Nonlinear Systems
2013	
Jan. – Apr. 2013	Digital Control
Jan. – Apr. 2012	Control Theory II
	<i>McGill University:</i>
Jan. – Jun. 2011	Design Project I and II, undergraduate level
Jan. – Apr. 2011	ECSE 507 (Optimization and Optimal Control, graduate level)
Sep. – Dic. 2010	ECSE 404 (Control Systems, undergraduate level)
	<i>Graduated students</i>
Aug. 2021	Master, Bryan Rojas. Tuning an observer–predictor for nonlinear systems with delayed controls, codirected with Sabine Mondié (Cinvestav)

- Sep. 2020 Ph.D., Gian Gómez. Sliding modes and geometric representations: control of rigid bodies, codirected with Jorge Dávila (ESIME-IPN, Mexico)
- Dec. 2016 Ph.D., Félix Miranda. Robust control techniques by using nonsmooth convex analysis
- Aug. 2016 Master, Carlos Tovar. Design of neuromorphic circuits using singularity theory, codirected with Alessio Franci (UNAM)
- Dec. 2015 Ph.D., Debbie Hernández. Sliding-mode control of implicit systems, codirected with Alexander Poznyak (Cinvestav)
- Nov. 2015 Master, Pedro Flores. Control of a quadrotor in an unstructured environment, codirected with Pedro Castillo (Heudyasic, France)
- Nov. 2014 Master, Christopher Cruz. Agent coordination by reference conditioning, codirected with Jorge Dávila
- Nov. 2013 Master, Edgar Estrada. Passivity-based control of systems with delays, codirected with Sabine Mondié
- Nov. 2012 Master, Félix Miranda. Optimal LQ control for a class of systems with piecewise constant inputs, codirected with Vadim Azhmyakov (Cinvestav)

Professional associations

- IEEE Institute of Electrical and Electronics Engineers, Control Systems Society, since 2006
- SIAM Society for Industrial and Applied Mathematics, since 2007

Personal skills and competences

Additional training

- HYCON-EECI
- 2009 The Behavioral Approach to Modeling and Control. Paolo Rapisarda and Jan C. Willems
Nonlinear Output Regulation. Alberto Isidori
- 2008 Robotics, Geometry and Control. Ravi Banavar
- 2007 Modeling Analysis and Design of Hybrid Control Systems. Joao Pedro Hespanha
Nonlinear Adaptive Control with Applications. Alessandro Astolfi
Switched Systems and Control. Daniel Liberzon
- CTS-HYCON
- 2006 Stability and Stabilisation of Time-Varying Systems. Antoine Chaillet
Optimality, Stabilization and Feedback in Nonlinear Control. Francis Clarke
Hybrid Control Systems. Christophe Prieur

Mother tongue(s)

Spanish

Other languages

English

277 / 300 TOEFL

French

TCF 536 / 699 level 5 C1

Awards

- 2022 Member of the National System of Researchers (SNI), Researcher Level II, Mexico
- 2017, 2016, 2013 Promotion to researcher levels 3C, 3B and 3A, respectively. By Cinvestav
- 2018, 2014, 2011 Member of SNI, Researcher Level I
- 2009, 2005 Ph.D and master degrees with summa cum laude
- 1995 – 1997 Scholarship by *Programa de Alto Rendimiento Académico* at the Engineering Faculty, a program with the objective of creating high academic competition
- 1993 Third place at Mexico City's contest for the Seventh National Mathematical Olympics. Given by the Academy of Scientific Research and the Mexican Mathematics Society

Publications

Journal papers

(1 IEEE TIE, 5 Automatica, 5 IEEE TAC, 2 SIAM SICON, 1 SIAM SIADS, 5 Syst. Control Lett., 2 Int. J. Robust Nonlin., 2 Int. J. Control, 2 EJC, 1 Circuits Syst. Signal Process., 1 IMA J. Math. Control. Info., 1 Neurocomputing, 1 J. R. Soc. Interface)

Emanuel Rocha, Fernando Castaños, and Jaime A. Moreno.

Robust finite-time stabilisation of an arbitrary-order nonholonomic system in chained form.

Automatica, 135:109956, January 2022

Fernando Castaños and Sabine Mondié.

Observer-based predictor for a susceptible-infectious-recovered model with delays: An optimal-control case study.

Int. J. Robust Nonlinear Control, 31:5118 – 5133, July 2021

Marco Tulio Angulo, Fernando Castaños, Rodrigo Moreno-Morton, Jorge X. Velasco-Hernández, and Jaime A. Moreno.

A simple criterion to design optimal non-pharmaceutical interventions for mitigating epidemic outbreaks.

J. R. Soc. Interface, 18:20200803, 2021

Dmitry Gromov and Fernando Castaños.

Self-oscillations in an alpha Stirling engine: a bifurcation analysis.

SIAM J. Appl. Dyn. Sys., 19:1865 – 1883, August 2020

Félix Miranda, Fernando Castaños, and Bernard Brogliato.

Continuous and discrete-time stability of a robust set-valued nested controller.

Automatica, 107:406 – 417, September 2019.

Nominated by the editor

Fernando Castaños, Edgar Estrada, Sabine Mondié, and Adrián Ramírez.

Passivity-based PI control of first-order systems with I/O communication delays: a frequency domain analysis.

Int. J. Control, 91:2549 – 2562, November 2018

Félix Miranda, Bernard Brogliato, and Fernando Castaños.

Set-valued sliding-mode control of uncertain linear systems: Continuous and discrete-time analysis.

SIAM J. Control Optim., 56:1756 – 1793, May 2018

Félix Miranda, Bernard Brogliato, and Fernando Castaños.

Multivalued robust tracking control of Lagrange systems: Continuous and discrete-time algorithms.

IEEE Trans. Autom. Control, 62:4436 – 4450, September 2017

Fernando Castaños and Alessio Franci.

Implementing robust neuromodulation in neuromorphic circuits.

Neurocomputing, 233:3 – 13, April 2017

Félix Miranda and Fernando Castaños.

Robust output regulation of strongly passive linear systems with multivalued maximally monotone controls.

IEEE Trans. Autom. Control, 62:238 – 249, January 2017

Debbie Hernández-Zárate, Fernando Castaños, and Leonid Fridman.

Zero-dynamics design and its application to the stabilization of implicit systems.

Systems and Control Lett., 98:74 – 78, December 2016

Andrea Aparicio Martínez, Fernando Castaños, and Leonid Fridman.

Output feedback sliding-mode control with unmatched disturbances, an ISS approach.

Int. J. Robust Nonlinear Control, 26:4056 – 4071, December 2016

Félix Miranda, Fernando Castaños, and Alexander Poznyak.

Min–max piecewise constant optimal control for multi-model linear systems.

IMA J Math Control Info, 33:1157 – 1176, December 2016

Fernando Castaños and Dmitry Gromov.

Passivity-based control of implicit port-Hamiltonian systems with holonomic constraints.

Systems and Control Lett., 94:11 – 18, August 2016

- Fernando Castaños and Cristian Kususch.
Ditherless extremum seeking for hydrogen minimization in PEM fuel cells.
IEEE Trans. Ind. Electron., 62:5218 – 5226, August 2015
- Manuel Mera, Fernando Castaños, and Alexander Poznyak.
Quantised and sampled output feedback for nonlinear systems.
Int. J. Control, 87:2475 – 2487, December 2014
- Fernando Castaños, Debbie Hernández-Zárate, and Leonid Fridman.
Integral sliding-mode control for linear time-invariant implicit systems.
Automatica, 50:971 – 975, March 2014
- Fernando Castaños, Dmitry Gromov, Vincent Hayward, and Hannah Michalska.
Implicit and explicit representations of continuous-time port-Hamiltonian systems.
Systems and Control Lett., 62:324 – 330, April 2013
- Matteo Rubagotti, Antonio Estrada, Fernando Castaños, Antonella Ferrara, and Leonid Fridman.
Integral sliding mode control for nonlinear systems with matched and unmatched perturbations.
IEEE Trans. Autom. Control, 56:2699 – 2704, November 2011
- Fernando Castaños and Leonid Fridman.
Dynamic switching surfaces for output sliding mode control: An \mathcal{H}_∞ approach.
Automatica, 47:1957–1961, September 2011
- Fernando Castaños.
Discussion on: “Energy shaping of port-Hamiltonian systems by using alternate passive input-output pairs”.
European Journal of Control, 16:678 – 679, December 2010
- Fernando Castaños and Romeo Ortega.
Energy-balancing passivity-based control is equivalent to dissipation and output invariance.
Systems and Control Lett., 58:553 – 560, August 2009
- Fernando Castaños, Romeo Ortega, Arjan J. van der Schaft, and Alessandro Astolfi.
Asymptotic stabilization via control by interconnection of port-Hamiltonian systems.
Automatica, 45:1611 – 1618, July 2009
- Fernando Castaños, Bayu Jayawardhana, Romeo Ortega, and Eloísa García-Canseco.
Proportional plus integral control for set-point regulation of a class of nonlinear RLC circuits.
Circuits Syst. Signal Process., 28:609 – 623, August 2009
- Romeo Ortega, Arjan J. van der Schaft, Fernando Castaños, and Alessandro Astolfi.
Control by interconnection and standard passivity-based control of port-Hamiltonian systems.
IEEE Trans. Autom. Control, 53:2527 – 2542, December 2008
- Eugenii Shustin, Leonid Fridman, Emilia Fridman, and Fernando Castaños.
Robust semiglobal stabilization of the second order system by relay feedback with an uncertain variable time delay.
SIAM J. Control Optim., 47:196 – 217, January 2008
- Bayu Jayawardhana, Romeo Ortega, Eloísa García-Canseco, and Fernando Castaños.
Passivity of nonlinear incremental systems: Application to PI stabilization of nonlinear RLC circuits.
Systems and Control Lett., 56:618 – 622, September 2007
- Fernando Castaños and Leonid Fridman.
Analysis and design of integral sliding manifolds for systems with unmatched perturbations.
IEEE Trans. Autom. Control, 51:853 – 858, May 2006
- Yuri Orlov, Leonid Fridman, and Fernando Castaños.
Discussion on: “Dynamic sliding mode control for a class of systems with mismatched uncertainty”.
European Journal of Control, pages 11–18, 2005
- Book chapters
- Ismael Castillo, Fernando Castaños, and Leonid Fridman.
Sliding surface design for higher-order sliding modes.
In Leonid Fridman, Jean-Pierre Barbot, and Franck Plestan, editors, *Recent Trends in Sliding Mode Control*, chapter 1.2, pages 29 – 57. The Institution of Engineering and Technology, Herts, United Kingdom, 2016

Conferences

Fernando Castaños, Jian-Xin Xu, and Leonid Fridman.
Integral sliding modes for systems with matched and unmatched uncertainties.
In Christopher Edwards, Enric Fossas Colet, and Leonid Fridman, editors, *Advances in Variable Structure and Sliding Mode Control*, chapter 11, pages 227 – 246. Springer-Verlag, Berlin, 2006

8 CDC (IEEE, international), 11 IFAC (international), 1 ACC (international), 1 CCE (IEEE, international), 1 ICUAS (international), 1 IFAC (regional), 4 ECC (regional), 5 VSS (IEEE-IFAC, international), 1 CDC-ECC (international), 1 SICE-ISCS (international), 5 AMCA (national)

Fernando Castaños and Dmitry Gromov.
Limit cycles in locally Hamiltonian systems with dissipation.
In *Proc. IFAC Workshop on Lagrangian and Hamiltonian Methods for Nonlinear Control*, pages 201 – 206, Berlin, Germany, November 2021

Fernando Castaños, Félix Miranda, and Alessio Franci.
A notion of equivalence for linear complementarity problems with application to the design of non-smooth bifurcations.
In *Proc. IFAC World Congress*, pages ID-1340, Berlin, July 2020

Oscar B. Cieza, Fernando Castaños, and Johann Regger.
Implicit IDA-PBC for underactuated mechanical systems: An LMI-based approach.
In *Proc. Conference on Decision and Control*, pages 7770 – 7775, Nice, France, December 2019

Gian Carlo Gómez-Cortés, Fernando Castaños, and Jorge Dávila.
Sliding motions on $SO(3)$, sliding subgroups.
In *Proc. Conference on Decision and Control*, pages 6954 – 6958, Nice, France, December 2019

Gian Carlo Gómez-Cortés, Fernando Castaños, and Jorge Dávila.
Control en la esfera S^2 usando modos deslizantes.
In *Congreso Nacional de Control Automático*, pages 778 – 784, Puebla, Mexico, October 2019

Pedro Flores-Palmeros, Pedro Castillo, and Fernando Castaños.
Backstepping-based controller for flight formation.
In *International Conference on Unmanned Aircraft Systems*, pages 254 – 260, Atlanta, GA, June 2019

Emanuel Rocha, Jaime A. Moreno, and Fernando Castaños.
Homogeneous generalisation of the Lur'e problem and the circle criterion.
In *Proc. IFAC Conf. on Modelling, Identification and Control of Nonlinear Systems*, pages 514 – 519, Guadalajara, Mexico, June 2018

Dmitry Gromov, Fernando Castaños, and Alexander L. Fradkov.
Projected dynamics of constrained Hamiltonian systems.
In *Proc. European Control Conference*, pages 1277 – 1281, Limassol, Cyprus, June 2018

Dmitry Gromov and Fernando Castaños.
Control of driftless systems using piecewise constant inputs.
In *Control Systems (SICE ISCS), 2018 International Symposium on*, pages 226 – 231, Tokyo, Japan, March 2018

Emanuel Rocha, Jaime A. Moreno, and Fernando Castaños.
Generalización homogénea del problema de Lur'e y del criterio del círculo.
In *Congreso Anual de la AMCA*, pages 96 – 101, Monterrey, Mexico, October 2017

Félix Miranda, Fernando Castaños, and Bernard Brogliato.
A set-valued nested sliding-mode controller.
In *Proc. IFAC World Congress*, pages 3026 – 3031, Toulouse, France, July 2017

Félix Miranda, Bernard Brogliato, and Fernando Castaños.
Set-valued discrete-time sliding-mode control of uncertain linear systems.
In *Proc. IFAC World Congress*, pages 10017 – 10022, Toulouse, France, July 2017

Dmitry Gromov and Fernando Castaños.
The geometric structure of interconnected thermo-mechanical systems.
In *Proc. IFAC World Congress*, pages 584 – 589, Toulouse, France, July 2017

Félix Miranda and Fernando Castaños.
Robust output regulation of linear passive systems using maximally monotone controls.
In *Proc. Conference on Decision and Control*, pages 6897 – 6902, Osaka, Japan, December 2015

Fernando Castaños and Alessio Franci.
The transition between tonic spiking and bursting in a six-transistor neuromorphic device.
In *Proc. Int. Conf. on Electrical Eng., Computing Science and Automatic Control*, pages 1 – 6, Mexico City, Mexico, December 2015

Andrea Aparicio Martínez, Fernando Castaños, and Leonid Fridman.
ISS properties of sliding-mode controllers for systems with matched and unmatched disturbances.
In *Proc. European Control Conference*, pages 2870–2875, Linz, Austria, July 2015

Fernando Castaños and Dmitry Gromov.
Interconnection and damping assignment for implicit port-Hamiltonian systems.
In *Proc. IFAC Conf. on Modelling, Identification and Control of Nonlinear Systems*, pages 1016 – 1021, Saint Petersburg, Russia, June 2015

Andrea Aparicio Martínez, Fernando Castaños, and Leonid Fridman.
ISS-Lyapunov functions for output feedback sliding modes.
In *Proc. Conference on Decision and Control*, pages 5536 – 5541, Los Angeles, California, USA, December 2014

Debbie Hernández-Zárate, Fernando Castaños, and Leonid Fridman.
Pole-placement in higher-order sliding-mode control.
In *Proc. IFAC World Congress*, pages 1386 – 1391, Cape Town, South Africa, August 2014

Félix Miranda and Fernando Castaños.
Robust output regulation of variable structure systems with multivalued controls.
In *Proc. Variable Structure Systems Workshop*, Nantes, Francia, June 2014

Andrea Aparicio Martínez, Fernando Castaños, and Leonid Fridman.
Dynamic surface for output feedback sliding modes, the case of relative degree two.
In *Proc. Conference on Decision and Control*, pages 3578 – 3583, Florence, Italy, December 2013

Andrea Aparicio Martínez and Fernando Castaños.
Control por modos deslizantes por retroalimentación de salida con grado relativo dos.
In *Congreso Anual de la AMCA*, pages 544 – 549, Ensenada, Mexico, October 2013

Edgar Estrada, Fernando Castaños, and Sabine Mondié.
 σ -estabilidad de sistemas de control basados en pasividad con retardos en la comunicación.
In *Congreso Anual de la AMCA*, pages 129 – 134, Ensenada, Mexico, October 2013

Cristian Kunusch and Fernando Castaños.
On the implementation of an adaptive extremum seeking algorithm for hydrogen minimization in PEM fuel cell based systems.
In *Proc. European Control Conference*, pages 2501 – 2506, Zürich, Switzerland, July 2013

Cristian Kunusch and Fernando Castaños.
Extremum seeking algorithms for minimal hydrogen consumption in PEM fuel cells.
In *Proc. American Control Conference*, pages 1146 – 1151, Washington, DC, USA, June 2013

Fernando Castaños, Debbie Hernández-Zárate, and Leonid Fridman.
Integral sliding-mode control for linear time-invariant implicit descriptions.
In *Proc. Conference on Decision and Control*, pages 6442 – 6447, Maui, Hawaii, December 2012

Matteo Rubagotti, Antonio Estrada, Fernando Castaños, Antonella Ferrara, and Leonid Fridman.
Optimal disturbance rejection by integral sliding mode control for systems in regular form.
In *Proc. Variable Structure Systems Workshop*, pages 78 – 82, Mexico City, Mexico, June 2010

Fernando Castaños and Romeo Ortega.
Energy-balancing passivity-based control is equivalent to dissipation and output invariance.
In *Proc. European Control Conference*, page WeC2.4, Budapest, Hungary, August 2009

Eugenii Shustin, Leonid Fridman, Emilia Fridman, and Fernando Castaños.
 Robust semiglobal stabilization of the second order system by relay feedback with an uncertain variable time delay.
 In *Proc. Conference on Decision and Control*, pages 2716 – 2721, Cancún, México, December 2008

Fernando Castaños, Romeo Ortega, Arjan J. van der Schaft, and Alessandro Astolfi.
 Asymptotic stabilization via control by interconnection of port-Hamiltonian systems.
 In *Congreso Latinoamericano de Control Automático*, Mérida, Venezuela, November 2008

Fernando Castaños, Bayu Jayawardhana, Romeo Ortega, and Eloísa García-Canseco.
 A class of nonlinear RLC circuits globally stabilizable by proportional plus integral controllers.
 In *Proc. IFAC World Congress*, pages 6202 – 6207, Seoul, Korea, June 2008

Romeo Ortega, Arjan J. van der Schaft, Fernando Castaños, and Alessandro Astolfi.
 Control by (state-modulated) interconnection of port-Hamiltonian systems.
 In *Proc. IFAC Symposium on Nonlinear Control Systems*, pages 47 – 54, Pretoria, South Africa, August 2007

Bayu Jayawardhana, Romeo Ortega, Eloísa García-Canseco, and Fernando Castaños.
 Passivity of nonlinear incremental systems: Application to PI stabilization of nonlinear RLC circuits.
 In *Proc. Conference on Decision and Control*, page ThIP2.17, San Diego, December 2006

Fernando Castaños and Leonid Fridman.
 Design of integral sliding manifolds for multi-model uncertain systems via LMI.
 In *Proc. Variable Structure Systems Workshop*, pages 63–67, Alghero, Italy, June 2006

Fernando Castaños and Leonid Fridman.
 Robust design criteria for integral sliding surfaces.
 In *Proc. Conference on Decision and Control, and European Control Conference*, pages 1976–1981, Seville, Spain, December 2005

Fernando Castaños and Leonid Fridman.
 Integral sliding surface design using an \mathcal{H}_∞ criterion for decentralized control.
 In *Proc. IFAC World Congress*, pages Th–A09–T0/2, Prague, July 2005

Fernando Castaños and Leonid Fridman.
 Measurement sliding mode- \mathcal{H}_∞ control with application to decentralized systems.
 In *Proc. Variable Structure Systems Workshop*, Vilanova i la Geltrú, Spain, September 2004

Leonid Fridman, Fernando Castaños, N. M'Sirdi, and Khraef.
 Decomposition and robustness properties of integral sliding mode controllers.
 In *Proc. Variable Structure Systems Workshop*, Vilanova i la Geltrú, Spain, September 2004

Fernando Castaños and Leonid Fridman.
 Control descentralizado por modos deslizantes.
 In *Congreso Anual de la AMCA*, pages 253–258, México, D.F., 2004

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